

DISCOVERY MULTISENSOR DETECTOR



Part n. 5000-400

The Discovery Multisensor construction is similar to that of the optical detector but uses a different lid and optical mouldings to accommodate the thermistor (heat sensor). The sectional view (Fig2.) shows the arrangement of the optical chamber and the thermistor.

The Discovery Optic al/Heat Multisensor Detector contains an optical smoke sensor and a thermistor temperature sensor whose outputs are combined to give the final analogue value. The way in which the signals from the two sensors are combined depends on the response mode sele-

cted. The five modes provide response beha viour which incorporates heat detection, pure pure smoke detection and a combination of both. The multisensor is therefore useful over the widest range of applications.

The signals from the optical smoke sensing element and the temperature sensor are independent, and repre sent the smoke level and air temperature the respectively in the vicinity of the detector. The detector's micro co ntroller processes the two signals according to the mode selected. When the detector is

operating as a multisensor (i.e. modes 1, 3 and 4) the temperature signal processing extracts only rate-of-rise information for combi nation with the optical signal. In these modes the detector will not respond to а slow temperature increaseeven if the temperature reaches a high level. A large sudden change in temperature can, however, cause an alarm without the presence of smoke, if sustained for 20 seconds.

Additional heat sensor information Discovery **Optical/Heat Multisensor** Detectors allow access to unprocessed temperature information.The raw temperature data can be used in conjunction with the analogue value to enhance alarm signal processing and provide an additional level of safety.

The exact method of polling to make use of this feature is described in a technical document available to panel partners.

The processing algorithms in modes 1 to 4 incorporate drift compensation.

With reference to Table 2 the characteristics of the five response modes are summarised below.

Mode 1 has very high smoke sensitivity combined with high heat sensitivity. This gives a high overall sensitivity to both smouldering and flaming fires.

Mode 2 has a smoke sensitivity similar to that normal optical of а detector. This smoke mode is therefore equivalent to a standard optical detector. It is suitable for applications in which wide temperature changes occur under normal conditions.

Mode 3 has moderate smoke sensitivity combined with a moderate sensitivity to heat. This combination is considered the optimum for most general applications since it offers good response to both smouldering and flaming fires.



Mode 4 has lower than normal smoke sensitivity combined with high heat sensitivity. This makes it suitable for applications in which a certain amount of fumes or smoke is considered normal.

Mode 5 has no smoke sensitivity at all, but gives a pure heat detector response meeting the response time requirements for a Class A1R detector in the European standard EN 54-5. In this mode the detector will respond to slowly changing

temperatures and has a "fixed temperature" alarm threshold at 58°C. The analogue value in this mode will give the approximate air temperature over the range 15°C to 55°C.

In mode 5, the smoke sensor is still active though it does not contribute to the analogue signal. As a consequence, if the detector is used in a dirty or smoky environment the optical sensor drift flag may be activated in the heat-only mode.

Notes

1. This applies only to fire control panels which have been programmed to read the additional information.

2. In situ testing of the Multisensor detector should be carried out as

for smoke detectors in response mode 2 and for heat detectors in response mode 5. Both optical and heat sensors must be tested in modes 1,3 and 4.

3. If the Multisensor is to be used in mode 5, heat detector spacing/ coverage should be applied

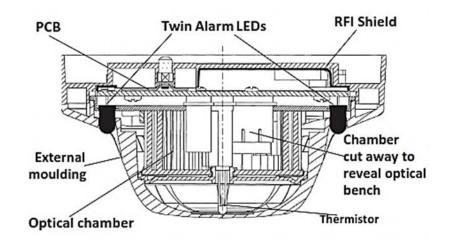


Figure 2 Discovery Multisensor Detector sectional view

Mode	Sensitivity to Grey Smoke (%/m) (dB/m)	Temperature Sensitivity	Response Type	Minimum Time to Alarm (seconds)
1	1.1 0.05	>15°C increase	Multisensor	20
2	2.1 0.09	Not set to heat response	Optical	30
3	2.8 0.12	>21°C increase	Multisensor	20
4	4.2 0.19	>15°C increase	Multisensor	20
5	No response to smoke	See mode 5 opposite	Heat A1R	15

TECHNICAL DATA

Discovery Multisensor Detector					
Part No. 5000-400					
Specifications are typical at 24V, 23°C and 50% relative humidity unless otherwise stated.					
Detector principle:	Smoke: Photo-electric detection of light scattered by				
	smoke particles				
	Heat: Temperature-dependent resistanc	e			
Supply wiring:	Two-wire supply, polarity insensitive				
Terminal functions: L1 & L2 supply in and out connections					
+R resistance to positive)	remote indicator positive connection (internal 2	.2kΩ			
-R	remote indicator negative connection (internal 2.2k Ω re	sistance to			
negative)					
Operating voltage:	17–28V DC				
Communication protocol:	Discovery, XP95 & CoreProtocol compatible				
5-9V peak to peak					
Quiescent current:	470μΑ				
Power-up surge current:	1mA				
Maximum power-up time:	10s				
Alarm current, LED illuminated:	3.5mA				
Remote output characteristics:	Connects to positive line through $4.5k\Omega$ (5mA maximum)				
Clean-air analogue value:	23 +4/-0				
Alarm level analogue value:	55				
Alarm indicator:	2 colourless Light Emitting Diodes (LEDs); illuminated red				
	in alarm. Optional remote LED				
Temperature range:	-40°C to 70°C				
Humidity:	0% to 95% RH (no condensation or icing)				
Vibration, impact & shock:	EN 54-5				
Designed to IP Rating:	IP54 in accordance with BS EN 60529				
Standards & approvals:	EN 54-5, LPCB				
Dimensions:	100mm diameter x 42mm height				
	(50mm height with XPERT 7 Mounting Base)				
Weight:	Detector	105g			
	Detector with XPERT 7 Mounting Base	160g			
Materials:	Housing White polycarbonate UL94-V0				
Constant and an	Terminals Nickel plated stainless steel				
Smoke element only:	Horizontal antical banch bouring infra rad amittan and				
Chamber configuration:	Horizontal optical bench housing infra-red emitter and				
Concort	sensor, arranged radially to detect forward scattered light				
Sensor:	Silicon PIN photo-diode				
Emitter:	GaAlAs infra-red light emitting diode				
Sampling frequency:	1 per second				